





Stylus Profiler

# User Manual

Innovation with Integrity

Stylus and Optical Metrology

# **DektakPro**

# **STYLUS PROFILER**

# **USER MANUAL**



P/N 980-510

©2024, Bruker Corporation All rights reserved Printed in the United States of America March 20, 2024

#### **COPYRIGHT NOTICE**

The reproduction, transmission, or use of this document or its contents is not permitted without express written authority. Offenders will be liable for damages. All rights reserved.

All configurations and specifications are subject to change without notice.

### TRADEMARK NOTICE

Vision64 is a registered trademark of Bruker Corporation. All other brand or product names are trademarks or registered trademarks of their respective holders.

Bruker Nano Surfaces Business 101 Daggett Drive San Jose, CA 95134 Phone: +1 866-262-4040 productinfo@bruker.com

# WARRANTY

### **Bruker Corporation Statement of Limited Warranty**

This product is covered by the terms of the Bruker Corporation standard warranty as in effect on the date of shipment and as reflected on the Bruker Order Acknowledgement and Quote. While a summary of the warranty statement is provided below, please refer to the Order Acknowledgement and/or Quote for a complete statement of the applicable warranty provisions. In addition, a copy of these warranty terms may be obtained by contacting Bruker.

**WARRANTY.** Seller warrants to the original Buyer that new equipment will be free of defects in material and workmanship for a period of one year commencing (a) on final acceptance or (b) 90 days from shipping, whichever occurs first. This warranty covers the cost of parts and labor (including, where applicable, field service labor and travel required to restore the equipment to normal operation).

Seller warrants to the original Buyer that replacement parts will be new or of equal functional quality and warranted for the remaining portion of the original warranty or 90 days, whichever is longer.

Seller warrants to the original Buyer that software will perform in substantial compliance with the written materials accompanying the software. Seller does not warrant uninterrupted or error-free operation.

Seller's obligation under these warranties is limited to repairing or replacing at Seller's option defective nonexpendable parts or software. These services will be performed, at Seller's option, at either Seller's facility or Buyer's business location. For repairs performed at Seller's facility, Buyer must contact Seller in advance for authorization to return equipment and must follow Seller's shipping instructions. Freight charges and shipments to Seller are Buyer's responsibility. Seller will return the equipment to Buyer at Seller's expense. All parts used in making warranty repairs will be new or of equal functional quality.

The warranty obligation of Seller shall not extend to defects that do not impair service or to provide warranty service beyond normal business hours, Monday through Friday (excluding Seller holidays). No claim will be allowed for any defect unless Seller shall have received notice of the defect within thirty days following its discovery by Buyer. Also, no claim will be allowed for equipment damaged in shipment sold under standard terms of F.O.B. factory. Within thirty days of Buyer's receipt of equipment, Seller must receive notice of any defect that Buyer could have discovered by prompt inspection. Products shall be considered accepted 30 days following (a) installation, if Seller performs installation, or (b) shipment; unless written notice of rejection is provided to Seller within such 30-day period.

Expendable items, including, but not limited to, lamps, pilot lights, filaments, fuses, mechanical pump belts, Vbelts, wafer transport belts, pump fluids, O-rings and seals ARE SPECIFICALLY EXCLUDED FROM THE FOREGOING WARRANTY AND ARE NOT WARRANTIED. All used equipment is sold 'AS IS, WHERE IS,' WITHOUT ANY WARRANTY, EXPRESS OR IMPLIED. Seller assumes no liability under the above warranties for equipment or system failures resulting from (1) abuse, misuse, modification or mishandling; (2) damage due to forces external to the machine including, but not limited to, acts of God, flooding, power surges, power failures, defective electrical work, transportation, foreign equipment/attachments or Buyer-supplied replacement parts or utilities or services such as gas; (3) improper operation or maintenance or (4) failure to perform preventive maintenance in accordance with Seller's recommendations (including keeping an accurate log of preventive maintenance). In addition, this warranty does not apply if any equipment or part has been modified without the written permission of Seller or if any Seller serial number has been removed or defaced.

No one is authorized to extend or alter these warranties on Seller's behalf without the written authorization of Seller.

THE ABOVE WARRANTIES ARE EXPRESSLY IN LIEU OF ANY OTHER EXPRESS OR IMPLIED WARRATIES (INCLUDING THE WARRANTY OF MERCHANTABILITY), AND OF ANY OTHER OBLIGATION ON THE PART OF SELLER. SELLER DOES NOT WARRANT THAT ANY EQUIPMENT OR SYSTEM CAN BE USED FOR ANY PARTICULAR PURPOSE OR WITH ANY PARTICULAR PROCESS OTHER THAN THAT COVERED BY THE APPLICABLE PUBLISHED SPECIFICATIONS.

**NO CONSEQUENTIAL DAMAGES. LIMITATION OF LIABILITY.** Seller shall not be liable for consequential damages, for anticipated or lost profits, incidental, indirect, special or punitive damages, loss of time, loss of use, or other losses, even if advised of the possibility of such damages, incurred by Buyer or any third party in connection with the equipment or services provided by Seller. In no event will Seller's liability in connection with the equipment or services provided by Seller exceed the amounts paid to Seller by Buyer hereunder.

Buyer is advised that, if the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

**Notices:** The information in this document is subject to change without notice. No Liability is assumed for errors contained herein or of incidental or consequential damages in connection with the furnishing, performance, or use of the material.



# TABLE OF CONTENTS

Chapter 1. Safety
Safety Features
Red Emergency Off Button
White Power On Button and Black Power Off Button
Safety Precautions
Safety and Health Hazards
Mechanical Hazards
Pressure Hazards
Installation and Maintenance Safety Issues1-4
General Lockout/Tagout Procedures1-5
Lockout Procedure
Returning the System to Operation
Electrical Task Classification1-5
Chapter 2. System Overview 2-1
How the System Works
Stage Configurations
Profiler Components
Measurement Head
Sensor Head and Stylus Assembly
Sample-Positioning Stage
Scan Stage
Electronics
Base Feet
Environmental Enclosure
EMO Box
Computer and Software
Options and Accessories
Chapter 3. Basic Operations and Maintenance 3-1
Powering Up the System
Powering Down the System
Loading and Unloading the Sample

Loading the Sample	3-4
Unloading the Sample	3-5
Towering Up and Down	3-5
Adjusting the Illumination.	3-5
Using the Manual Stage-Positioning Controls	3-6
Adjusting the X-Y Position.	3-6
Leveling the Stage	3-6
Using the Auto Stage-Positioning Controls	3-7
X-Y Control Panel	3-7
Theta Control Panel	3-9
Removing an Installed Stylus	3-10
Installing a Different Stylus	3-13
Cleaning the Stylus Tip	3-16
Electronically Configuring and Calibrating the Profiler	3-17
General Care and Maintenance	3-17
Chapter 4. Taking Measurements and Analyzing Data	4-1
Setting the Measurement Options	4-2
Settings on the Measurement Options Tab.	4-2
Taking a Standard Manual 2D Measurement	4-4
What Happens During a Scan Measurement	4-7
Creating an Automation Recipe that Includes Deskew Points	4-10
Appending Analytical Functions	4-13
Setting the Cursor Locations and Bandwidths.	4-14
Applying Software Leveling	4-16
Creating a Database	4-18
Creating an Analyzer Recipe	4-20
Using the Data Analyzer and Analysis Toolbox	4-20
Setting the Parameters for an Analysis or Filter	4-22
Selecting the Meta Data	4-22
Creating a Vision Recipe	4-22
Viewing and Analyzing Stored Data	4-23
Chanter 5 Using Vision64	5-1
	5 1
Marking With Vision Views	
Changing the Units and Other User Preterences	5-10

Performing Analyses	
Chapter 6. Wafer Warpage Mapping	6-1
Principle	
Getting started with Wafer Warpage Map	
Measurement length	
Scan time	
Force	
Start Radial Map	
Set Radial Map settings	
Define center of sample	
Launch Measurement	
Analyze topography	
Analyze stress	6-6
Troubleshooting	
Strong edge effects	6-7
Shape distortion	6-7
Chapter 7. Automatic Step Measurement	7-1
Setup	
Analysis	7-3

# 1

# SAFETY

The DektakPro<sup>TM</sup> system may be set up and operated only in accordance with the instructions outlined in this manual. In the chapters that follow, the messages below indicate that special vigilance is required.



#### CAUTION

Whenever you see a Caution note, there is a possibility that data will be lost, or there is some specific action that you must perform for the system to work properly.



WARNING Whenever you see a Warning note, there is the possibility of personal injury or equipment damage.

### **SAFETY FEATURES**

Several features of the DektakPro system ensure operator safety.

### **Red Emergency Off Button**

The DektakPro system is equipped with a red EMERGENCY OFF button, located on the EMO box (see Figure 1-1). This unit may be placed in any convenient and readily accessible location.

Pressing the EMERGENCY OFF button shuts off DC power to the system devices, excluding the computer, monitor, and power supply adapter. The 24 VDC control circuit in the EMO Box also remains energized.



Figure 1-1: EMO Box



### White Power On Button and Black Power Off Button

The DektakPro system is equipped with a white POWER ON button and a black POWER OFF button. These buttons are located next to the red EMERGENCY OFF button on the EMO Box (see Figure 1-1).

Pressing the POWER ON button provides DC power to all system devices but the computer, monitor, and power supply adapter.

Pressing the POWER OFF button shuts off DC power to all system devices but the computer, monitor, and power supply adapter. The 24 VDC control circuit in the EMO Box also remains energized.

### SAFETY PRECAUTIONS

The DektakPro system is designed to minimize potential health and safety hazards during normal operation and routine maintenance activities. As with any mechanical system that uses electrical energy and compressed air, it contains some physical and electrical hazards. You should be aware of these potential hazards and the controls used to minimize them. Review this section and contact Bruker if you have any questions on environmental, health, or safety-related issues associated with the system.

Potential safety hazards associated with the system are clearly identified in this manual. In addition, warning and safety labels have been placed on the system where there exists a potential for personal injury or damage to the system.

### SAFETY AND HEALTH HAZARDS

Although the DektakPro system has been designed with safety in mind, it does contain some inherent potential hazards. Physical hazards associated with operating the equipment are discussed in this section.

### **Mechanical Hazards**

Mechanical hazards exist in the systems wherever moving parts are located, such as slides. Protection against most of the mechanical hazards in the DektakPro system is provided in the form of a hood and system base. Wherever possible, physical guards have been placed around moving parts to prevent personnel from contacting them. The exceptions are the areas around and above the X-Y stage. These areas, however, do not contain pinch-point hazards.

Some maintenance tasks may require removal of the hood and system base. In these cases, safe work practices, including use of lockout procedures for electricity, pressure (pneumatic system) or other applicable hazards, should be followed. Only trained service personnel should perform maintenance activities that require mechanical motion while the hood and base are removed.

### **Pressure Hazards**

Pressure hazards exist due to the difference in kinetic energy of a gas within a container or piping system and the surrounding environment. If a sudden breach of a gas line or a pressurized container were to occur (for example, a gas delivery line bursts), the pressure differential between the gas in the line and the surrounding atmosphere will cause the gas to be forcefully expelled into the surrounding atmosphere. This can cause physical injuries due to particles flying outward with extremely high speed.

The DektakPro system uses compressed clean dry air (CDA) to operate the optional vibration isolation table. It is designed to use CDA at the typical house-supplied pressures of 50 psi. The CDA fittings or components of the pneumatic system should be adjusted only after appropriate release of air-line pressure. As with electrical and mechanical tasks, maintenance activities involving the air lines should occur only after appropriate pressure lockout procedures have been implemented (see General Lockout/Tagout Procedures in the section that follows).

### **INSTALLATION AND MAINTENANCE SAFETY ISSUES**

Certain installation activities require attention to special safety hazards in addition to the overall system hazards discussed in the Safety and Health Hazards section above. The installation of the systems requires connection and adjustment of electricity and pressurized air lines. These types of activities require knowledge and use of lockout/tagout procedures.

Maintenance procedures often present greater hazards to personnel than normal production activities due to the need to defeat safety features in order to access the equipment. The following sections present general information on some of the key safety-related procedures or actions that maintenance personnel should follow when servicing the DektakPro system.

### **General Lockout/Tagout Procedures**

This section describes general lockout/tagout procedures for electrical systems and pressurized air lines. Contact your internal safety and health representative for more detailed procedures for your facility, as well as for training and authorization/certification requirements.

#### Lockout Procedure

- 1 Notify all affected and other persons of intended lockout.
- 2 Turn off the computer following the normal shutdown procedure.
- 3 Unplug the first cord on the power supply adapter from its receptacle on the signal processor on the back of the DektakPro stylus profiler.
- 4 Unplug the second cord on the power supply adapter from its wall outlet.
- 5 Place the power supply adapter with its two disconnected cords in a secure location. This is the equivalent of a lockout/tagout procedure on a more complex system.
- 6 Close the air regulator toggle switch below the vibration isolation table.
- 7 Dissipate any residual pressure following the appropriate dissipation procedure (for example, opening a bleed valve).
- 8 Verify that all personnel are clear of the hazard zone.
- 9 Attempt to restart the equipment. If properly locked out the equipment should not be able to be started.
- 10 Use a voltmeter and make voltage measurements to verify that all electrical sources have been locked out. If properly locked out, no voltage should be present. Check the reading on supply line pressure gauges to verify that no pressure exists within the system. If properly locked out, no pressure should exist.
- 11 Perform maintenance work.

### **Returning the System to Operation**

- 1 Verify that all personnel, materials, tools, and test equipment are clear of the hazard zone.
- 2 Plug the first cord on the power supply adapter into its receptacle on the signal processor on the back of the DektakPro stylus profiler.
- 3 Plug the second cord on the power supply adapter into a wall outlet.
- 4 Open the air regulator toggle switch to repressurize the vibration isolation table.
- 5 Turn on the computer following the normal startup procedure.
- 6 Notify all affected and other persons that the lockout has been cleared and the equipment is back in operation.

### **Electrical Task Classification**

Each task involving electrical operations is evaluated for severity and classified according to the criteria outlined in Table 1-2. These criteria categorize electrical hazards into four types, ranging from Type 1 (de-energized) to Type 4 (fully energized and exposure required). Lockout/tagout requirements, including training requirements, are based on the type of hazard present.

- All operator tasks are classified as Type 1 or 2.
- Only qualified service personnel should perform Type 3 or 4 tasks, following established Bruker service policies.

Task Type	Description		
Туре 1	Equipment is fully de-energized		
Туре 2	Equipment is energized. Energized circuits are covered or insulated.		
Туре 3	Equipment is energized. Energized circuits are exposed and inadvertent contact with uninsulated energized parts is possible. Potential exposures are no greater than 30 volts rms, 42.4 volts peak, 60 volts DC or 240 volt-amps in dry locations.		
Туре 4	Equipment is energized. Energized circuits are exposed and inadvertent contact with uninsulated energized parts is possible. Potential exposures are greater than 30 volts rms, 24 volts peak, 60 volts DC, or 240 volt-amps in dry locations. Potential exposures to radio-frequency currents, whether induced or via contact, exceed certain limits.		

#### Table 1-2: Classification of Operator Tasks

**NOTE** – No routine tasks for the DektakPro system are classified as Type 4.

During any troubleshooting or maintenance activities that are performed while the DektakPro system is operating, the technician should always be able to easily reach the EMERGENCY OFF button on the EMO Box (see Figure 1-1). In case of an emergency, the technician can press the EMERGENCY OFF button to immediately stop the system.

In some circumstances, it is advisable to have two service personnel working on a system at the same time. This ensures that one person will always have access to the EMERGENCY OFF button.



2

### SYSTEM OVERVIEW

The DektakPro<sup>®</sup> stylus surface profiler is an advanced thin and thick film step height measurement tool. In addition to profiling surface topography and waviness, the DektakPro system measures roughness in the nanometer range. Available with a standard manual sample-positioning stage (see Figure 2-1) or an optional automatic X-Y or theta stage (see Figure 2-3), it provides a step-height repeatability of 5Å (<0.6 nm).

In addition to taking two-dimensional surface profile measurements, the DektakPro system can produce three-dimensional measurements and analyses when equipped with the 3D Mapping Option.



Figure 2-1: DektakPro Stylus Profiler with the Standard Manual X-Y Sample-Positioning Stage

### **HOW THE SYSTEM WORKS**

The DektakPro system takes measurements electromechanically by moving a diamond-tipped stylus over the sample surface according to a user-programmed scan length, speed, and stylus force. The stylus is linked to a Linear Variable Differential Transformer (LDVT), which produces and processes electrical signals that correspond to surface variations of the sample. After being converted to digital format, these surface variations are stored for display and analysis.

The Vision64 application calculates and displays the results of user-selected analytical functions for measuring surface texture and other parameters to characterize the profile data. For example, the Ra (average roughness) analytical function—the most commonly used international parameter of roughness—calculates the arithmetic average deviation from the mean line within the assessment length. If there is an active database, selected analytical functions are logged to it during each measurement.

### **STAGE CONFIGURATIONS**

The DektakPro stylus surface profiler comes in the following stage configurations:

- The standard 2-D DektakPro system, which includes a two-axis, manual sample-positioning stage with 101.6 x 101.6 mm (4 x 4 inches) of X-Y translation, manual leveling, two-point programmable or cursor software leveling, and manual theta rotation (see Figure 2-2). This standard stage accommodates samples up to 50 mm (1.9 inches) thick and performs long scans of 55 mm (2.16 inches). It provides ± 50.8 mm (2 inches) of X-Y translation as well as manual theta positioning (see Figure 2-3). The standard system is available with 50 mm (1.97 inch), 100 mm (3.94 inch), and 150 mm (5.90 inch) wafer alignment pins, along with one of the following sample fixtures (chucks):
  - 101 mm (4-inch) square base platform with no vacuum capability
  - Ceramic vacuum
  - Dedicated photo voltaic vacuum



Figure 2-2: Standard Manual Sample-Positioning Stage with Square Base Platform Fixture

- The 3D Mapping and Automation Options, which include an X-Y auto sample-positioning stage (see Figure 2-3). In addition to 3D mapping (see Figure 2-15), these options provide automation and programmability of up to 200 sites on samples of up to 150 mm (5.90 inches) in diameter. The X-Y auto sample-positioning stage includes one of the following sample fixtures (chucks):
  - 50 mm to 76 mm (2 to 3 inch) wafer vacuum
  - 101 mm to 152 mm (4 to 6 inch) wafer vacuum
  - Dedicated 203 mm (8-inch) wafer vacuum
  - Ceramic vacuum
  - Dedicated photo voltaic vacuum



Figure 2-3: X-Y Auto Stage with Wafer Vacuum Sample Fixture (Chuck)

### **PROFILER COMPONENTS**

As shown in Figure 2-1, the DektakPro stylus surface profiler system contains all of the mechanical, electrical, and optical components for sample positioning, sample viewing, and scanning/measurement. As described in Stage Configurations on page 2-2, the system can be configured with a manual or X-Y auto stage. Its sturdy single-arch bridge design reduces sensitivity to adverse environmental conditions.

### **Measurement Head**

The hood-covered measurement head shown in Figure 2-1 houses a USB video camera and an LED illuminator to assist the operator in feature location and stylus centering. The live video output of the camera provides feedback to the operator during a scan measurement.

The measurement head also includes a sensor head that magnetically holds the stylus assembly and contains the feedback mechanisms required to track stylus movement as it rides over the sample surface.



#### WARNING

Do not remove the hood and attempt to service the components of the yourself. Instead call Bruker Customer Service. Failure to heed this warning can result in damage to delicate equipment.

### Sensor Head and Stylus Assembly

A diamond-tipped stylus (see Figure 2-3) attached to the sensor head permits accurate twodimensional surface profiler measurements in a wide range of applications. In standard configuration, user-programmable stylus force from 1 mg to 15 mg allows profiling on soft or hard surfaces.

A variety of available stylus tip sizes are available to fill a broad range of measurement applications. Each tip comes in its own protective case.

**NOTE** – The DektakPro system comes with a stylus exchange tool that allows you to safely exchange one stylus for another without damaging the delicate tip.



Figure 2-4: Sensor Head and Stylus Assembly

### Sample-Positioning Stage

Available sample-positioning stages and sample fixtures (chucks) are discussed in Stage Configurations on page 2-2.

### Scan Stage

The direct-drive scan stage accelerates measurements by reducing the time between scans. This allows for the generation of large 3D maps or long scans for measuring stress.

### **Electronics**

The DektakPro system includes a power supply adapter with an input voltage 100 - 240 VAC (see Figure 2-5). This unit sends power to the various system components.

A signal processor provides monitoring and control of the LVDT signal, stylus force coil, stage motor, and LED illumination (see Figure 2-6). An integrated cable connector panel handles system input, output, and power signals.

Power demand is 110 VA maximum with a standard outlet power connection.



Figure 2-5: Power Supply Adapter



Figure 2-6: Signal Processor

### **Base Feet**

The standard urethane polymer base feet (see Figure 2-7) help isolate the system from the surrounding vibrational environment.



Figure 2-7: Standard Base Foot

The optional passive pneumatic isolation feet (see Figure 2-8) accept compressed air or nitrogen. These feet can be used in place of a large vibration isolation system.



Figure 2-8: Isolation Base Foot

### **Environmental Enclosure**

The acrylic environmental enclosure (see Figure 2-9) protects the sample and scan area from adverse outside influences such as noise, vibrations, dust, and air currents. The front door lifts to provide sample access. The system should always be operated with the enclosure door closed.



### **EMO Box**

An Emergency Machine Off box (EMO Box) includes POWER OFF and POWER ON buttons, along with an EMERGENCY OFF button (see Figure 2-10). The EMERGENCY OFF button cuts off power to the DektakPro system but leaves power on to the computer and monitor. After the EMERGENCY OFF button has been depressed, the power cannot be returned to the system until it has been released. This is accomplished by turning it clockwise by one-eighth turn.



Figure 2-10: EMO Box

### **COMPUTER AND SOFTWARE**

The DektakPro system can include the optional Dell<sup>™</sup> computer, keyboard, mouse, and DVD drive. If you prefer to used your own preferred computer it must fill the following requirements:

- The computer must be capable of running the Windows 10/11 operating system
- The monitor must have a 16 x 9 aspect ratio and minimum display resolution 1920 x 1080.

The pre-loaded Vision64 measurement and analysis software (see Figure 2-11) has 64-bit parallel-processing architecture. It allows you adjust the system illumination, position a sample under the stylus, take single-scan or automated measurements (see Figure 2-12), calculate analytical functions, apply analyses and filters, and perform special operations, such as comparing the analytical results from multiple scans. For an introduction to Vision64, see Chapter 5 of this manual. For full instructions on using the Vision64 software, see the DektakPro online Help.



Figure 2-11: The Vision64 Welcome Screen



Figure 2-12: Output Display for a Single-Scan Measurement

### **OPTIONS AND ACCESSORIES**

A number of options and accessories are available for the DektakPro system, including:

• A video monitor that provides a 24-inch, high-resolution, flat-panel color display (see Figure 2-13). It shows programs and graphics in full color, along with a color video image of the sample surface from the USB camera in the tower assembly.



Figure 2-13: Video Monitor

- The X-Y auto stage described in Stage Configurations on page 2-2.
- A broad line of calibration standards (see Figure 2-14).



Figure 2-14: Step Height Standard

- A variety of styli for measuring fine surface features and softer samples.
- Stress Measurement for calculating tensile or comprehensive stress on processed wafers.
- The 3D Mapping Option that enables true 3D-mapping (see Figure 2-15), calculates the bearing ratio, and performs many other analyses.
- 200-mm (7.8 inch) data-stitching software for increasing the scan length to 150 mm or longer with multiple stitching operations (available only on systems that include the X-Y auto stage).



Figure 2-15: 2D Contour Plot Generated with the 3D Mapping Option



3

# **BASIC OPERATIONS AND MAINTENANCE**

This chapter describes the basic use of your DektakPro stylus surface profiler, including the software procedures that involve profiler control. For instructions regarding other software procedures, see Chapter 5 of this manual and the Vision64 online Help.

### **POWERING UP THE SYSTEM**

The following steps include all possible startup contingencies. Normally you can simply press the white ON button on the EMO Box, turn on the computer and monitor, and then start the Vision64 software.

To power up the DektakPro system:

- 1 Verify that the cable from power supply adapter is connected to a wall outlet.
- 2 Verify that all USB cables are connected.
- 3 Verify that the software key is installed in a USB port of the computer (see Figure 3-1). (The software key is shipped inside the Vision64 CD case.)



Figure 3-1: Software Key in a USB Port

4 Verify that the red Emergency Off button on the EMO Box is in the On (popped-up) position. If it is not, release it by rotating it clockwise until it pops up (see Figure 3-2).



Figure 3-2: Releasing the Red Emergency Off Button on the EMO box

- 5 Press the white ON button on the EMO Box. After you do this, the following events occur:
  - The white ON button on the EMO box illuminates (see Figure 3-3).



Figure 3-3: EMO Box with Illuminated On Button

- All system devices are powered up with the exception of the computer and monitor.
- The light bar at the back of the profiler Illuminates.
- The red LED lights on the scan stage limit switches illuminate.
- 6 Press and release the power button on the front of the computer.
- 7 Turn on the monitor and power up the computer.
- 8 Select Start > Vision64 or click the Vision64 application button on the desktop or task bar. As the software launches, the following events occur:
  - The tower assembly moves to its upper limit. The system stops with the stylus in the Tower Up position.
  - The scan stage initializes. You can now safely position the sample beneath the stylus.
  - The Vision64 Welcome screen appears, followed by the Vision64 **Instrument** tab, which includes the DektakPro Live Video Display (see Figure 3-4).
- 9 Allow the system to warm up for approximately 15 minutes before taking a scan measurement.



Figure 3-4: Vision64 Instrument Tab, Including the Live Video Display

### **POWERING DOWN THE SYSTEM**

**IMPORTANT SAFETY INFORMATION!** The DektakPro system is equipped with a red EMERGENCY OFF button located on the EMO Box connected to the back of the profiler (see Figure 3-4). You may place this box in any convenient and readily accessible location. Pressing the EMERGENCY OFF button immediately shuts off power to all system components, excluding the computer, monitor, and power supply adapter. The 24 VDC control circuit in the EMO Box also remains energized. After you power down the system via the EMO box, you must exit Vision64, shut down the computer, and turn off the monitor as described below.



Figure 3-5: Red EMO and Black Off buttons on the EMO box

To power down the DektakPro system:

- 1 Close the Vison64 software as described in Closing Vision64 on page 5-1.
- 2 Press the black OFF button on the EMO Box (see Figure 3-5). This shuts off power to all system devices but the computer, monitor, power supply adapter, and 24 VDC control circuit in the EMO Box.
- 3 Select Start > Shut Down from the Windows Start menu, and then click Shut Down in the dialog box that appears.
- 4 Turn off the monitor.

### LOADING AND UNLOADING THE SAMPLE



#### WARNING

If the sample does not freely clear the stylus, click the Tower Up is to raise the stylus so that it is safely above the sample. Failure to do so can damage both the stylus and the sample.

### Loading the Sample

Click the **Unload Sample** button and the toolbar above the Live Video Display to move the scan stage forward 55mm (two inches). You can now conveniently place a sample on the sample fixture (see Figure 3-6) remove it without risk of damage to the stylus or the sample.

Click the **Load Sample** button  $\checkmark$  to move the scan stage backward its home position. Use the manual or auto stage controls to fine-position the area of interest on the sample beneath the stylus. For instructions, see Using the Manual Stage-Positioning Controls on page 3-6 and Using the Auto Stage-Positioning Controls on page 3-7.



Figure 3-6: Sample Loaded on the Theta Sample Fixture (Chuck)

### **Unloading the Sample**

When a scan routine is complete, the stylus automatically lifts off the surface. To remove the sample, from the fixture, click the **Unload Sample** button *stape* to make the system move the sample-positioning stage forward. You can now lift your sample off the fixture.

### **TOWERING UP AND DOWN**

You must slowly lower the tower assembly to bring the feature that you want to measure into focus in the Live Video Display. To do this, click the **Tower Down** button on the toolbar above the Live Video Display.

To raise the tower assembly, click the Tower Up raise button.

To bring the tower all the way up to its home position, click the **Tower Home** button  $\left| \stackrel{\scriptstyle \sim}{=} \right|$ .

**NOTE** – The DektakPro profiler automatically towers down to bring the stylus into contact with the sample whenever you start a single-scan measurement, 3D map scan, or automation program.



WARNING

The tower assembly has a total travel range of 50mm, so sample heights must not exceed 50mm.

### **ADJUSTING THE ILLUMINATION**

After lowering the tower to focus the camera on your sample, you must adjust the illumination level of the video image displayed on the monitor. To do this, move the slider on the Intensity Bar at the bottom of the right pane of the Live Video Display (see Figure 3-7). Move it to the right to increase the illumination and to the left to decrease it. The feature that you want to scan should be clearly illuminated.

**NOTE** – When you save a Vision recipe, the illumination level is automatically included along with the other measurement settings.



Figure 3-7: Intensity Bar

### **USING THE MANUAL STAGE-POSITIONING CONTROLS**

If your DektakPro system includes the manual sample-positioning stage (see Figure 3-8), you must use the procedures described in this section to adjust both the X and Y positions.

### **Adjusting the X-Y Position**

To position a sample using the manual sample-positioning stage controls:

- 1 Ensure the stylus is not touching the sample surface. If it is, click the **Tower Up** button on the toolbar.
- 2 Position the scan start site by using the X-Y positioning levers.
  - Pull the lever below the front of the platform for coarse X movement.
  - Pull the lever below the left side of the platform for coarse Y movement.
  - Use the respective knobs to finely position the sample.



X coarsepositioning Lever

Figure 3-8: X-Y Positioning Levers on the Manual Sample-Positioning Stage

**NOTE** – After fine-tuning the scan site using the X and Y positioning levers, you may have to re-null the tower to adjust for skew. (To re-null the tower, tower up and then tower down.)

### Leveling the Stage

All stage configurations of the DektakPro system allow you to manually level the samplepositioning stage by turning the leveling knob below it (see Figure 3-9). The closest possible manual leveling ensures the best profiler performance. Guidelines for leveling the stage appear after the picture.



Figure 3-9: Stage-Leveling Knob

As you perform manual stage leveling, follow these guidelines:

- To view the effect of leveling on the profile trace in real time, perform stage leveling while a scan measurement is in progress.
- To verify that the maximum possible level has been obtained, position the cursors so that they intersect the same horizontal plane.
- If the profile trace is extremely off-level, change the measurement range to 5240kÅ. Level the trace, change to the intermediate range, and then repeat the procedure until the stage is leveled. The best level is achieved by using the 6.5kÅ range.

### **USING THE AUTO STAGE-POSITIONING CONTROLS**

When you open Vision64, the Live Video Display appears by default. On its right-hand side, it contains two instrument control panels—the X/Y Control Panel and the Theta Control Panel.

### X-Y Control Panel

Prior to a taking measurement, you must position the area of interest on the sample under the stylus by adjusting the X-Y position of the motorized sample-positioning stage. Instructions for doing this appear after the figure.



Figure 3-10: X-Y Stage Control Panel

To set the X-Y position of the motorized sample-positioning stage:

In the X-Y Control Panel in the Live Video Display (see Figure 3-10), click the blue Gear icon in the upper right corner to enter the select the units as well as the speeds for Fast, Medium, and Slow (see Figure 3-11). If you select the Grab Circle to Move check box, you must grab the red circle in the middle of the X-Y Control Panel before you can adjust the X/Y position of the motorized stage. When your settings are complete, click OK.

XY Options		
Display Units	Millimeter	•
Fast Speed	15	mm/s 🔻
Medium Speed	7.5	mm/s 🔻
Slow Speed	1	mm/s 🔻
	🔲 Grab Cir	cle To Move?
	Show Stag	je Rectangle?
ОК	Ca	ncel

Figure 3-11: X/Y Options Dialog Box

- 2 In the lower right corner, click the speed at which you want the stage to travel.
- 3 Do one of the following:
  - Holding down the left mouse button, drag the red dot in the center of the cross hairs. The dot becomes an
    arrow that you can drag with the cursor. The real time X and Y positions of the stage appear in the boxes

at the lower left. Click and drag to move the stage to another area of interest and display it in the Live Video Pane. When you have obtained the correct stage position, release the mouse button.

 Click the Edit Mode button . Either type your locations in the X and Y fields or click the Move button to move the stage to those locations.

### **Theta Control Panel**

Prior to a taking measurement, you must place the area of interest on the sample under the stylus by adjusting the position of the motorized theta sample-positioning stage. Instructions for doing this appear after the figure.



Figure 3-12: Theta Stage Control

To set the position of the motorized theta sample-positioning stage:

1 In the Theta Control Panel in the Live Video Display (see Figure 3-12), click the blue Gear icon in the upper right corner to enter the units as well as the speeds for Fast, Medium, and Slow on both the R Axis and the Theta Axis (see Figure 3-13). If you select the Grab Rectangle to Move check box, you must grab the red rectangle in the middle of the Theta Control Panel before you can adjust the theta position of the motorized stage. When your settings are complete, click OK.

RThetaStageOptions					
R Axis Settings					
Display Units	Millimeter 🔻				
Fast Speed	10 mm/s 🔻				
Medium Speed	5 mm/s 🔻				
Slow Speed	0.5 mm/s 🔻				
Theta Axis Settings	Theta Axis Settings				
Display Units	Degree 🔻				
Fast Speed	10 deg/s 🔻				
Medium Speed	1 deg/s ▼				
Slow Speed	0.1 deg/s 🔻				
Grab Rectangle To Move?					
	OK Cancel				

Figure 3-13: RTheta Stage Options Dialog Box

- 2 Holding down the left mouse button, drag the red bar in the center of the ring. The bar becomes an arrow that you can drag with the cursor. The real time theta position of the stage appears in the box below the ring. This position is graphically depicted by the moving red indicator on the yellow ring.
- 3 When you have obtained the correct stage position, release the mouse button.

### **REMOVING AN INSTALLED STYLUS**

When a stylus becomes worn or you want to measure another type of sample, you must remove the currently installed stylus from the sensor head (see Figure 3-14) before replacing it with a different one.



Figure 3-14: Sensor Head and Stylus on the DektakPro Profiler

To remove a stylus from the sensor head on the DektakPro profiler:

1 Locate the protective case in which the stylus was shipped and place it near the DektakPro stylus profiler (see Figure 3-15).



Figure 3-15: Protective Stylus Case

- 2 Locate the black plastic stylus exchange tool (see Figure 3-18) and place it near the stylus case.
- 3 Tower up to the Home position 5 to allow room for maneuvering.
- 4 On the profiler, turn the brass thumbscrew on the left side of the sensor head counter-clockwise to loosen the sensor head magnetic shield (see Figure 3-16).





- 5 Slip the shield off the pin on the right side of the sensor head.
- 6 Carefully move the shield toward the front of the profiler and pull it off the sensor head, making sure to avoid contact with the stylus.



Figure 3-17: Magnetic Shield Removed from Sensor Head

7 Rotate the thumbscrew on the stylus exchange tool so that a gray circle (NOT a green one) is visible and the magnet is NOT engaged (see Figure 3-18).



Figure 3-18: Stylus Exchange Tool with Its Magnet Disengaged

- 8 Position the stylus exchange tool beneath the sensor head (see Figure 3-19).
- 9 Holding the stylus exchange tool by its sides, align the alignment pins on its top with the outside of the front of the sensor head (see Figure 3-19). Gently push up until the tool is flush with the bottom of the sensor head. The ridge at the back of the stylus exchange tool must roughly line up with the back of the sensor head. The stylus tip should extend out through the front of the channel on the exchange tool.



Figure 3-19: Stylus Exchange Tool Flush with the Bottom of the Sensor Head



#### WARNING

Avoid any personal contact with the stylus arm or tip. This can result in damage to the stylus.

- 10 Rotate the thumbscrew on the left side of the stylus exchange tool so that a green circle becomes visible and the magnet is engaged. The magnet now pulls the stylus into the channel on the exchange tool (see Figure 3-18). Lower the exchange tool containing the stylus from the bottom of the sensor head and take it to the protective case in which the stylus was shipped (see Figure 3-15).
- 11 To remove the stylus from the stylus exchange tool:
  - a. Disengage the magnet on the exchange tool by rotating the thumb wheel in either direction so that a gray circle replaces the green one.
- **b.** Using tweezers, gently grip the silver magnetic disk pad at the back of the stylus and then lift the stylus out of the channel on the stylus exchange tool.
- **c.** Place the stylus in its protective case with the tip pointing downward through the hole in the film in the lower part of the protective case (see Figure 3-20).



Figure 3-20: Inserting the Stylus Tip into the Hole in the Film in the Stylus Case



WARNING.

Always store the stylus in its protective case. Failure to do so can result in damage to the stylus.

## **INSTALLING A DIFFERENT STYLUS**

**NOTE** – The following instructions assume that you have already removed the magnetic shield from the sensor head on the DektakPro profiler. If this is not the case, follow steps 4 - 6 in the previous section.

- 1 Tower up to the Home position  $\left| \begin{array}{c} \mathbb{Z} \\ \mathbb{Z} \end{array} \right|$  to allow room for maneuvering.
- 2 Locate the stylus exchange tool. If its green circle is visible, rotate the thumbscrew in either direction to disengage the magnet and replace the green circle with a gray one. (This means that the magnet is NOT engaged as shown in Figure 3-21.)



Figure 3-21: Stylus Exchange Tool with Its Magnet Disengaged

3 Locate the case that holds the stylus that you want to install. After opening the case, use tweezers to gently lift the stylus holding ONLY THE SILVER MAGNETIC DISK PAD AT ITS BACK END (see Figure 3-22).



Figure 3-22: Lifting the Stylus from Its Case

- 4 Align the magnetic disk pad of the stylus with the magnetic disk pad on the stylus exchange tool (see Figure 3-21).
- 5 Seat the stylus in the channel on the exchange tool. The stylus arm should extend out through the front channel on the exchange tool (see Figure 3-23).

6 Rotate the thumb wheel on the left side of the stylus exchange tool counterclockwise to display the green circle and engage the magnet (see Figure 3-23).



#### Figure 3-23: Stylus Exchange Tool with a Stylus Seated in the Channel and the Magnet Engaged

7 Place the stylus exchange tool underneath the sensor head on the DektakPro profiler. Holding the stylus exchange tool by the sides, align the alignment pins on its top with the outside of the front of the sensor head (see Figure 3-24). Gently push up until the tool is flush with the bottom of the sensor head. The ridge at the back of the stylus exchange tool must roughly line up with the back of the sensor head.



Figure 3-24: Stylus Exchange Tool Flush with the Bottom of the Sensor Head

#### WARNING

Avoid any personal contact with the stylus arm or tip. This can result in damage to the stylus.

- 8 Disengage the magnet by rotating the thumbwheel in either direction so that a gray circle replaces the green one.
- 9 Lower the stylus exchange tool.
- **10** Position the magnetic shield on the thumbscrew shaft on the left side of the sensor head.

11 Turn the brass thumb screw clockwise to attach the magnetic shield as shown in Figure 3-25. Do not tighten the screw—just "snug" it.



Figure 3-25: Sensor Head with Magnetic Shield Attached

## **CLEANING THE STYLUS TIP**

- 1 Tower up to the Home position  $\begin{bmatrix} 3 \\ -5 \end{bmatrix}$  t.
- 2 If there is a sample on the chuck or stage, remove it.
- 3 Clean the stylus tip using a lint-free synthetic cotton swab, which will not leave any fibers on the stylus. Moisten the swab with deionized water or laboratory-grade isopropyl alcohol. Lightly touch the stylus tip with the synthetic cotton swab to remove any dust. You may also use a small soft-bristle paintbrush. Do NOT use an air gun.



## ELECTRONICALLY CONFIGURING AND CALIBRATING THE PROFILER

#### WARNING

Most of the settings available from the icons in the **Configuration** section of the Instrument toolbar should *NOT* be changed by the user without help from Bruker Customer Service. To reach Bruker Customer Service, call 800-873-9750.

To change the DektakPro hardware configuration settings:

1 On the Instrument tab of the Ribbon in Vision64, click one of the following icons to open its associated dialog box:



Figure 3-26: Configuration and Calibration Buttons on the Instrument Tab

- Click Advanced Setup to open a dialog box that allows you to make the settings for Soft Touchdown (which controls the gradual increase of the stylus force to a specified value) and Tower LVDT Phase and Force (which controls the production and processing of the electrical signals that correspond to surface variations of the sample). Call Bruker Customer Service for help in making your settings. When you are done, click OK.
- The **Stylus Force Calibration** wizard guides you through the process of calibrating the force with which the stylus tip contacts the sample.
- The Vertical Calibration wizard guides you through the procedure of taking a height or depth measurement and comparing the results with a calibration standard's certified value. An average measured value that is within ± 0.5% of the certified value ensures that your DektakPro system is taking accurate measurements.
- The Reset Dektak function initializes the scan stage.

**NOTE** – For a full explanation of all DektakPro configuration settings, see the Vision64 online Help.

## **GENERAL CARE AND MAINTENANCE**

Follow these guidelines:

- Do not use lubricants on the stage leadscrews.
- Always position the sample so that the stylus is the only part of the stylus assembly that touches the sample.

- Keep the environmental enclosure door closed both when the DektakPro system is in use and when it is not.
- Never connect or disconnect any cables when the power is on.
- Do not lower the tower without the stage assembly in place.
- Do not move a sample during a scan measurement.
- Avoid vibration and shock during measurements. For example, ensure that an operator does not bump a surface close to the profiler or the profiler itself during a measurement.
- Always raise the tower to the maximum vertical position when the system is not in use.



4

## TAKING MEASUREMENTS AND ANALYZING DATA

This chapter tells you how to take manual and automated scan measurements. It also explains the manipulation and analysis of scan data.



Figure 4-1: DektakPro System with an Open Enclosure Door

## SETTING THE MEASUREMENT OPTIONS

Before taking a manual measurement or an automated series of measurements, you must make selections in the **Measurement Setup** window (see Figure 4-2). If you save these selections as a Vision recipe that you designate as the default, the system will automatically apply them to every future measurement. For instructions, see Creating a Vision Recipe on page 4-22.

**NOTE –** If the **Measurement Options** window does not appear, click the **Measurement Setup** button on the Ribbon.

Aeasurement S	etup			_
leasurement O	ptions			
Trace				
Scan Type: (	Standard Scan	Length:	2000	μm Ҟ
Range: (	6.5 µm	Duration:	10	sec
Profile		Resolution:	0.667	μm/pt
FIOINE.		Sample:	3000	pts
Stylus Type: (	Radius: 12.5 µm	Speed:	200	μm/s
Stylus Force:	3 mg			
Additional Para	meters			
	📝 Tower Up After Scan 🗌	Use Soft Touch	down	
dvanced Option	ns			
ata Stitching				
D Map				

Figure 4-2: Measurement Options Tab of the Measurement Setup window

#### Settings on the Measurement Options Tab

Scan Type: Select from the following:

- **Standard Scan:** A normal scan type in which the scan is performed across the surface of a sample. Because the tower is nulled before each scan, each successive scan has its own reference point.
- **Static Tower Scan:** A special scan type in which the scan is performed across the surface of a sample, but the tower is nulled before only the first scan. Each successive scan therefore uses the same initial reference point.
- **Static Scan:** A special scan type in which the scan is performed at the same point. (The scan stage does not move.) The tower is nulled before the scan. This scan type is primarily used for determining the noise and drift of the system.
- **Map Scan:** If your system includes the 3D Mapping Option, select this scan type to measure, analyze, and view surface contour data in three dimensions (X, Y, and Z).

**Range:** Enter a value that indicates vertical resolution of the scan. When measuring extremely fine geometries, the 6.5 um range provides a vertical bit resolution of 0.1 nm. For general applications, the 1.0 nm vertical resolution of the 65.5 um range is usually adequate. When measuring thick films or very rough or curved samples, select the 524 um range with 8.0 nm resolution.

**NOTE** – The selected scan range is scaled across the LVDT output of the stylus head sensor and digitized. The greater the selected scan range, the lower the vertical resolution of the measurement. The 6.5um range will provide a vertical bit resolution of approximately 0.1nm. The 65.5um range has a resolution of 1nm, the 524um range has a resolution of 8nm, and the 1mm range has a vertical resolution of 15nm. So while the 65.5um, 524um, and 1mm scan ranges would all work for a 10um step, the 65.5um is the best.

**Profile**: Select from the following:

- Valleys: Provides 90% of the measurement range below the zero horizontal grid line. This option is used primarily for measuring etch depths.
- Hills and Valleys: Provides 50% of the measurement range above the zero horizontal grid line and 50% below. This option is used in most applications, especially if the surface characteristics of the sample are not well known, or if the sample is out of level.
- Hills: Provides 90% of the measurement range above the horizontal grid line. This option is used primarily for measuring step heights.

**NOTE** – When setting up ranges and scan profile types, always think about keeping the stylus trace from "topping out" or "bottoming out" in the Data Acquistion window.

Stylus Type: Select the currently installed stylus type from the drop-down list.

Stylus Force: Enter a value between 1 mg and 15 mg.

Length: Enter a scan length between 50 um and 55,000 um (55 mm) for a non-stitched measurement.

**Duration**: Enter amount of time it will take to complete a given scan. Scan duration, in conjunction with scan length, determines the horizontal resolution of a scan. For most applications, a 10 - 20 second scan provides adequate resolution and throughput.

**Resolution**: Enter the horizontal resolution for the scan length and scan duration. The scan resolution is expressed in um/sample, indicating the horizontal distance between data points.

**Sample**: Indicates the number of data points that the system should take on the sample during a measurement.

Speed: Indicates the scan speed in units of um/s.

**Tower Up After Scan:** Select this check box to make the DektakPro stylus profiler automatically raise the tower ti a safe position after each scan.

**Use Soft Touchdown:** If your system includes the 3D Mapping Option, select this check box to make the DektakPro stylus profiler increment the stylus force up to the specified value. This causes the stylus to descend more slowly, thus minimizing the possibility of scratching the sample.

**NOTE** – For instructions on making the settings on the **Advanced** Tab, see Creating an Automation Recipe that Includes Deskew Points on page 4-10. For instructions on making the settings on the **Data Stitching** and **3D Map** tabs, see your Vision64 online Help.

## **TAKING A STANDARD MANUAL 2D MEASUREMENT**

The most common measurement performed on the DektakPro system is a Standard manual 2D measurement, which consists of a single trace along the sample in the Y direction (that is, along the front-to-back axis). When the scan is complete, Vision64 provides an output of the two-dimensional trace, describing the height of surface features with an interactive Z versus Y plot.

The length of the trace that you can define depends upon the DektakPro stage that is installed. For a DektakPro system with the manual 150mm X-Y stage, the standard scan length can range from 50um minimum to 55mm maximum. For a DektakPro system equipped with an automated 150mm XY stage, the standard scan length can range from 50um minimum to 200mm maximum. Scan lengths from 55mm to 200mm use the DektakPro's data stitching capability, which is described in the online Help.

**IMPORTANT!** Always operate the DektakPro inside its acrylic environmental enclosure (see Figure 4-1). This enclosure protects the sample and scan area from adverse outside influences such as noise, vibrations, dust, and air currents. Always operate the system with the enclosure door closed.



#### WARNING

Always raise the tower prior to loading a sample. Failure to do so can damage the stylus and sample.

- 1 In the Vision64 Measurement Setup window, do one of the following:
  - If your system includes the X-Y or theta auto stage, click Unload Sample If your system includes the X-Y or theta auto stage, click Unload Sample If your system in the Live Video Display.
     The tower moves to its full upward position, and the stage moves to its full front (unload) position.
  - If your system includes the manual X-Y stage, click **Tower Up** in the Live Video Display and then use the manual stage controls to bring the stage to its full front position. For instructions, see Chapter 3.
- 2 Place the sample on the sample fixture (chuck). If you are measuring a wafer, this will be the vacuum wafer chuck. If your are measuring a solar sample, this will be the solar chuck. Otherwise, place the sample on the square base platform of the scan stage itself.
- 3 If your system includes a vacuum chuck, turn on the vacuum switch.
- 4 In the Live Video Display, click the Load Sample button position, ready for a measurement.

- 5 Click **Tower Down** in the Live Video Display. The tower lowers to the measurement position with the stylus down, and the stylus makes brief contact with the sample. The stylus then moves to its Up position.
- 6 If necessary, adjust the Intensity slider in the Live Video Display so that the sample is clearly illuminated.



Figure 4-3: Illumination Bar

- 7 Adjust the position of the X-Y or theta stage until you find the location of interest on your sample.
- 8 Fine-position the location of interest in the center of the Live Video Display.

**NOTE** – Since the stylus scans across the sample in the Y direction, it is important to position the features of your location of interest so that they are perpendicular to the scan direction. For example, if you are measuring a step height standard, the step must run horizontally across the Live Video Display. Samples such as metals should be positioned so that the lay (the predominant direction of the surface texture) runs horizontally across the Live Video Display.

**NOTE** – Because the scan will move "Up" in the Live Video Display, the trace must be positioned above the stylus, thus ensuring that it will be fully measured.

- 9 On the **Measurement Options** tab of the **Measurement Setup** window, select **Standard Scan** (see Figure 4-4).
- 10 If you do not want to use the default Measurement Options settings that are stored in your Vision recipe, change any other settings on the Measurement Options tab of the Measurement Setup window. For definitions of the parameters in the Measurement Options window, see Setting the Measurement Options on page 4-2.

**NOTE** – If your system includes the X-Y auto stage, click the **Teach** button is to the left of the **Length** field open a window that lets you drive the stage to the start-point of the scan.

Measurement S	etup			-
Measurement Op	otions			
Trace				
Scan Type: (	Standard Scan	<ul> <li>Length:</li> </ul>	2000	μm Ҟ
Range: (	6.5 µm	<ul> <li>Duration:</li> </ul>	10	sec
Desfler		Resolution:	0.667	μm/pt
Profile:		Sample:	3000	pts
Stylus Type: (	Radius: 12.5 µm	<ul> <li>Speed:</li> </ul>	200	μm/s
Stylus Force:	3 mg			
Additional Para	meters I Tower Up After Scan	Use Soft Touch	down	
Advanced Option	ns			
Data Stitching				
3D Map				

#### Figure 4-4: Measurement Options Window

- 11 Click the Advanced Options tab and make sure that the Number of Measurements is set to 1.
- 12 Click the **Measurement** button on the Ribbon (see Figure 4-5) and then select **Measurement**. The events that now occur are described in What Happens During a Scan Measurement on page 4-6.



Figure 4-5: Measurement Buttons

13 Observe the measurement in real-time in the **Data Acquisition** window. If the scan hits or exceeds the top or bottom border of the **Data Acquisition** window, adjust the tilt on the scan stage (see Figure 4-6) and/or increase the **Scan Range** value in the **Measurement Options** window.



Figure 4-6: Stage-Leveling Knob

14 At the end of the measurement, the Data Analysis window appears (see Figure 4-6). If desired, click **Save** > **Dataset**.

🔷 I 🜔 🔹 😮 I Vision6-				
Instrument	Analyze Preferences			
Measurement Pause C	Open Save Files	Trint Help Bruker.com iscellaneous	Reset on Dektak	ss Setet
Data Analysis			_×	Data Analyzer
				T2 7 1 2 0
100			Isabel         Value         R ss         R value         M value         M value           Totul_4341         672.64         513.03 and         720.05 and         122 and         123.24 and           Totul_94         123.04 min         513.03 and         720.05 and         527.86 and         127.86 and           Totul_94         123.04 min         512.04 min         727.05 and         527.86 and         72.95 and	Sandard Scan 24331 PM     Profile State     Profile State
-20-0	0.1 0.	0.2 0.3 0.4	v m , Watch List	Surface Profile Analysis Settings     Surface Profile Analysis Settings     Total Profile Reaginess Profile Warness Profile Other     Height Part Profile Reaginess Profile Conter     Profile Profile Profile Profile Profile Profile     Profile Profile Profile Profile     Profile Profile     Profile Profile     Profile Profile     Profil
			Label Value	Pq Pp Avg Height Slope Perim Psk Pv Radius
Total Profile	X-Axis: Min Max mm Y-Axis Min Max mm 19	Label         Position (mm)         Total Profile (n · · · Vrid R · · · · · · · · · · · · · · · · · · ·	1081/341 87.428 m	Port     Pr     Pr
Standard Scan 2:				
Ready	i D 🚸 🕅	<u>k</u> 🥳		

Figure 4-7: Data Analysis Window

## What Happens During a Scan Measurement

When a measurement begins, the tower assembly lowers and the stylus descends. You can see the stylus and its shadow in the Live Video Display (see Figure 4-7).



Figure 4-8: Live Video Display Showing the Descending Stylus and Its Shadow

After the stylus tip contacts the sample surface, it begins to scan over the surface features. The Live Video Display shows a real-time image of the stylus along with a measurement trace of the surface in the Data Aquisition window to the right (see Figure 4-8). It also provides the vertical and horizontal distances between the cursor/trace intercepts and the distances from the vertical and horizontal "zero" grid lines.

**NOTE** – If your system includes the 3-D Mapping package, or if the scan is set for Hill or Valley, the process described above is somewhat different. For example, during a measurement with the 3D Mapping package, a real-time picture of the sample appears during data collection (see Figure 4-9).

After the scan measurement is complete, the Data Analysis Display appears (see Figure 4-10). The surface features encountered by the stylus are represented as a two-dimensional profile. To the right, the output display shows a list of the scan parameters along with any user-requested analytical results. If you have created and activated a database, that database appears beside the Data Analysis display (see Figure 4-25).

At the end of the scan measurement, the tower and stylus automatically move back to their starting positions, and the system is immediately ready for the next measurement.



Figure 4-9: Live Video of the Stylus with the Real-Time Measurement Trace on the Right



Figure 4-10: Real-Time Picture of the Sample During a Measurement Taken with the 3D Mapping Package



Figure 4-11: Data Analysis Display

# CREATING AN AUTOMATION RECIPE THAT INCLUDES DESKEW POINTS

When you are developing an Automation recipe for a production reference sample, all programmed X and Y coordinates relate to the position of that particular sample as it rests on the stage. It is unlikely that you can load subsequent samples at the exact physical location of the reference point that was used to define the Automation recipe.

To compensate for such skewing, you can establish Deskew reference and measurement points on a reference sample at the time that the Automation recipe is defined. You may select any easily identifiable landmarks on the reference sample as Deskew points (for example, the test pads on a silicon wafer or substrate corners). When the system runs the Automation recipe, it refers to these Deskew points to correct for variations in the positions of your samples.

To create and run an Automation recipe that includes Deskew points:

- 1 Position your reference sample on the stage so that the area that you want to use as your Deskew reference point is visible in the Live Video Display. The Deskew reference point anchors the sample location to a fixed stage position.
- 2 Click the Automation Setup button 🥂 on the Ribbon. The Automation Editor appears.
- 3 Tower down
- 4 To set the Deskew reference point:
  - a. In the Live Video Display, drive the stage to the area that you want to use as the Deskew reference point.
  - b. In the Automation Editor, click Set Reference Point. A red circle enclosing an R now appears in that location (see Figure 4-12).



Figure 4-12: Setting the Deskew Reference Point

- 5 To set the Deskew alignment point:
  - a. Drive the stage to the area on the image that you want to use as the Deskew alignment point.
  - b. Tower down
  - c. In the Automation Editor, click the Add Alignment Site button. A solid red circle now appears at that location (see Figure 4-13).



Figure 4-13: Setting the Deskew Alignment Point

- 6 To program the measurement points:
  - a. Drive the stage to the area on the image that you want to use as the first measurement point.
  - b. Tower down
  - **c.** In the Automation Editor, click the **Measurement Site** button. A number outlined by a green circle now appears at that location (see Figure 4-14).
  - d. Repeat the above steps to define all further required measurement points.



Figure 4-14: Setting a Deskew Measurement Point

- 7 In the Automation Editor, select the **Align at Start of Automated Run** check box to activate the Deskew feature. The system will now automatically run the Deskew recipe prior running this Automation recipe.
- 8 If desired, change the Automation Options at the bottom of the Automation Editor (see Figure 4-15).



Figure 4-15: Options at the Bottom of the Automation Editor

- 9 Select Save > Automation Recipe. Name this recipe and then click Open.
- 10 Select Measurement > Automated Measurement. The system automatically runs the Deskew recipe followed by the Automation recipe.
- 11 As the measurement sequence initiates, an Automation Status message appears. Watch the live progress bar as the stage moves to the first location specified in the Automation recipe.
- 12 After the stylus arrives at each programmed point, you must use the Live Video Display and the Instrument Control Panel above it to tower down and align that point. The stylus then runs over the sample, and the stage moves to the next location specified in the Automation recipe.

- 13 At any time, you can click to cancel the automated sequence.
- 14 At the end of an automation run, a message informs you that the system has "Completed script named [Script Name]." Click **OK**.

## **APPENDING ANALYTICAL FUNCTIONS**

After you take a scan measurement, Vision64 can calculate a number of analytical functions for analysis of roughness, waviness, step height, and geometrical measurements. Frequently calculated functions include ASH (delta average step height), horizontal distance, and vertical distance. You can save your selection of analytical functions to a Vision recipe so that they are automatically calculated whenever you take a manual measurement or an automated series of measurements.

To select analytical functions:

1 On the Ribbon, click the Data Analysis icon



-

Append	
Delete	
Delete All	
Change ID	
Fundation (Analysis)	
export Analytical Results	S

#### Figure 4-16: Analytical Results Pop-Up Menu

3 Select Append. The following window appears.

Total Prof	ile Primary I	Profile				
Height			Hybrid	Geometry		
Pa Pq Psk Pku	Pz Pp Pv Pt	ASH Avg Height	🔲 Pdo	Area Slope Radius	Volume Perim	
Spatial						
Pc Psm						
Discr	imination Set	tings				
He	ight 10	% Pz				
Spa	acing 1	% Sampli	ng Length			
Zero i Use th Cursor P	mean data be he same settir ositioning	fore calculating ngs for raw, prir	parameter nary, rough	(s) ness, and wavines	S	
Label	Position (n	nm) Width (	mm)			
R	0.0000	0.0000				
м	1.9993	0.0000				
Δ	1.9993					
				Ca	lculate	Close

Figure 4-17: Analytical Functions window

- 4 Select your analytical functions and then enter the positions and bandwidths of the cursors that define the area in which the analytical functions should be calculated.
- 5 Click Calculate.

# SETTING THE CURSOR LOCATIONS AND BANDWIDTHS

The red reference (**R**) cursor and green measurement (**M**) cursor in the Data Analysis Display define the portion of the profile trace on which to calculate analytical functions on the measurement results (see Figure 4-18). You can adjust the bandwidth at each cursor to average the data points within that cursor's bandwidth. This is especially useful for average step height measurements.



Figure 4-18: 2D Profile of the Data Analysis Display Showing the R and M Cursors

To change the position of each cursor on the measurement data, click on it and then drag it with the mouse.

To change the bandwidth of a cursor, click it to display small boxes that you can then drag. To reposition the cursors while maintaining the same distance between them, click on one of the cursors, and then hold down the Alt key while dragging that cursor. The second cursor moves along with it.

The locations of the **R Cursor** and **M Cursor** and their bandwidths appear in a box at the bottom of the Data Analysis window (see Figure 4-7). To change these settings, type in new values and press **Enter**.

**NOTE** – The numbers in the Cursor Status box indicate the points at which the cursors intercept the profile trace in relation to the horizontal scale.

Label	Position (mm)	Total Profile (µ 🔻	Width (mm)
R	0.5362	0.0223	0.0000
м	1.4182	0.0372	0.0000
Δ	0.8821	0.0149	

Figure 4-19: Cursor Status Box

## **APPLYING SOFTWARE LEVELING**

Software leveling allows the system to quickly and automatically level the profile trace. You must software level the stage in order to obtain accurate step height measurements and accurate readings from analytical functions. Software leveling sets the reference and measurement cursors at zero to establish a reference for measurements.

To software level a trace from a live measurement in the Data Analysis window:

1 Click **Terms Removal (F-Operator)** in the Analysis Toolbox (see Figure 4-20) to add it to the Data Analyzer tree (see Figure 4-21).



Figure 4-20: Terms Removal (F-Operator) in the Analysis Toolbox



Figure 4-21: Terms Removal (F-Operator) in the Data Analyzer Tree

- 2 Position the R and M cursors as far apart as possible along the baseline of the step.
- 3 Right-click and select **Two-Point Linear Fit** rom the **Data Leveling Settings** pop-up menu (see Figure 4-22).
- 4 The profile trace re-plots and levels with the R and M cursor intercepts at zero.



Figure 4-22: Data Leveling Pop-up Menu

## **CREATING A DATABASE**

**NOTE** – Every time you change the selection of analytical functions that you want to log, you must create a new database.

To create a database:

- 1 Select the analytical functions, cursor positions, and analyses and filters that you want to include in this database.
- 2 Click the **Database Setup** button and then click **Create New File**. A **Save** window appears. Enter a name for your database and then click **Save**.
- 3 As shown in Figure 4-23, the **Database Setup View** window appears. The currently selected analysis flow is available from nested expandable lists in the upper right corner. A table to the left shows the parameters in the currently active database, whose path appears above the table.

Current Analysis Flow	C:\ProgramData	\Bruker\Vision\Database\KT1.csv		
Profile Stats AutoSelection	Result Name	Analysis Name	DisplayUnits	
CursorPosition	Total_P_ASH	Profile Stats:Segment 1.Total Profile	A	
Segment 1	Total_Pa	Profile Stats:Segment 2.Total Profile	A	
A Total Profile	Total_Pt	Profile Stats:Segment 2.Total Profile	A	
Units Category				
▲ Segment 2				
Settings				
<ul> <li>Iotal Profile</li> <li>Units Category</li> </ul>				
✓ TotalPa				
Terms Removal (E-Operator				
remain nemoral (i - operator	1			
	Move Up	Move Down		
	Appletical Parult	s Show Pass/Fail Use Template C	SV Remove Current CSV	1
Create New File Select All	Analytical Nesult			

Figure 4-23: Database Setup View window

4 The following buttons appear at the bottom of the **Database Setup View** window:

Create New File Select All Analytical Results Show Pass/Fail Use Template	CSV Remove Current CSV
---	------------------------

#### Figure 4-24: Buttons at the Bottom of the Database Setup View window

5 Click the desired button and make the appropriate entries.

**NOTE** – Click **Select All Analytical Results** to populate the database with the current selections or analysis parameters in the Analytical Results table.

- 6 Click **OK** in the **Database Setup** window.
- 7 Do one of the following:
  - Toggle to Database button on the Analyze Tab to Logging Enabled
     .
  - Click the **General Preferences** button in the **Preferences**, set **Enable Data Logging** to **True**, and then click **OK**. A database file is now generated for each scan measurement (see Figure 4-25).

		X Colabour			K Data Analysee
			Total P Auk	Test Pt	1 2 2 5 5 0
	Analytical Results		A	A	
	Free man inter states and inter	Meanarement Mander	Always	Always	1 11
March March 194	The set of the second s		Profile StatuSegment L'Istal Profile	Profile StatuSegment 2.Total Profile	a Destar from 12 2011 Aut
	Base in 1116 on 1111 and Man AVII and Man	1	711.09	711	4 Schedule
	Tanker Charles and the ball and an her be	1	737.28	713	e Miller
		1	720.55	72	4 "7 Serra Serra al P.
			722.85	128	Durille Lints
			73428	712	
			101.04	10.4	
			714.41	111	
		11	777.60	107	
		**	716.11	161	5
		14	729.28	3653	
		14	718.08	813	
		25	71712	71	
		24	724.58	77.4	
		17	728.45	66.5	
1004		38	720.86	(4.5	
		19	720.85	311.7	
		20	71837	719	Anatoria Tanàna
		21	721.28	47	1
		22	71879	720	
15 02 025 03 035		Arg	718.05	218.2	
	WANIM	Sv8	3175	303	
	Label Yake	Skewnene	-5.82	42	
		Mari	731.19	3628	
		blay.	514.00	451	-11
		Range	217.39	2002	
Max mm		Para	21	11	- 11
Max eve		1 I Date		P	
Max sun					
Mar mm		Detalation	Detabase Fu	nou(outry	
h Mar Poli		Eensilasies	fusoridationelZ •		

Figure 4-25: Data Analysis Display with an Open Database Window

## **CREATING AN ANALYZER RECIPE**

An Analyzer recipe contains your selected analytical functions, 2D analyses, and filters. If your system includes the 3D mapping package, it also contains the default plot and 3D analysis/filter flow.

**IMPORTANT!** The Analyzer recipe that is open when you save a Vision recipe becomes part of that Vision recipe. This means that the analyses and filters that it contains will automatically be applied to every future dataset. For more information, see Creating a Vision Recipe on page 4-22.

To create an Analyzer recipe:

- 1 Take a new scan measurement.
- 2 Select your analytical functions and cursor bandwidth settings as explained in Appending Analytical Functions on page 4-13 and Setting the Cursor Locations and Bandwidths on page 4-14.
- 3 Select your analyses and filters in the Analysis Toolbox as explained in the next section.
- 4 Click the **Open Database** button at the button of the Database window and then open the database that you want to associate with this Analyzer Recipe.
- 5 On any Ribbon tab, select **Save > Analyzer Recipe**.
- 6 To make this Analyzer recipe a part of the currently open Vision recipe, select the **Default Analyzer** check box on the toolbar on top of the Data Analyzer.

### Using the Data Analyzer and Analysis Toolbox

An Analyzer recipe is associated with each dataset and appears in the Data Analyzer (see Figure 4-26) whenever that dataset is active. An Analyzer recipe consists of the name of the active dataset, the dataset type (for example, Surface Height), the Raw Data analysis, and any other analyses and filters that have been selected in the Analysis Toolbox (see Figure 4-27).



Figure 4-26: Data Analyzer

Below the Data Analyzer, the Analysis Toolbox contains all of the analyses and filters that can be applied to a dataset (see Figure 4-27).



Figure 4-27: Analysis Toolbox

To apply an analysis or filter, click it in the Analysis Toolbox. The selected operation is immediately performed on the active scan dataset. In the Data Analyzer above the Analysis Toolbox, the operation now appears as part of the workflow tree (Analyzer recipe), as shown in Figure 4-28.



Figure 4-28: Workflow Tree that Includes Terms Removal (F-Operator) and Step Detection

**IMPORTANT!** After you click a second analysis (not a filter), the Analysis toolbox goes blank because you can perform only one analysis per branch. If you want to perform more than one analysis, click the **Profile Filter** branch and then add another analysis, which then becomes an additional branch of the Data Analyzer.

## Setting the Parameters for an Analysis or Filter

To set the default parameters for an analysis or filter, right-click its icon, click **Default Settings**, make your settings in the window that appears, and then click **OK**. The settings will now be applied during every future operation of this type.

## Selecting the Meta Data

To select the types of meta data to be stored with each dataset, click the **Meta Data** button in the Data Analyzer.

To view the meta data that is already associated with an active dataset, click the **Meta Data** button on the toolbar above the Data Analyzer.

## **CREATING A VISION RECIPE**

A Vision recipe contains all of the information that the system needs to make a single scan measurement. It also includes the Analyzer recipe that is active when you create and save the Vision recipe, so you can scan a sample and then visualize and analyze the resulting dataset with a single click.

To create and save a Vision recipe:

- 1 Select a scan type and make measurement selections in the **Measurement Setup** window.
- 2 Do one of the following:
  - To save this Vision recipe independently of the currently active Analyzer recipe, click **Save > Vision Recipe** on any Ribbon Tab.
  - To save the currently active Analyzer recipe as part of this Vision recipe, select the **Default Analyzer** check box on the Data Analyzer Toolbar and then click **Save > Vision Recipe** on any Ribbon Tab.
- 3 In the Save As window, enter a recipe name. The system supplies the file extension.
- 4 To save your settings as the default Vision recipe that the system will apply to every new scan measurement, select the **Set as the Startup Recipe** check box on top of the Data Analyzer.
- 5 Click Save.

## **VIEWING AND ANALYZING STORED DATA**

DektakPro measurement results are stored in files with an .opdx extension. To open one, select **Open** > **Dataset**.

Multiple stored datasets can be simultaneously opened and displayed in the Active Data Gallery (see Figure 4-29). Click a thumbnail image of a dataset to make it the active one in the Data Analysis window (standard DektakPro) or the Main Display Area (3D Mapping Option).

To apply filters and analyses to the active dataset, make selections in the Analysis Toolbox. For instructions, see Using the Data Analyzer and Analysis Toolbox on page 4-20.

To save any changes to the active dataset, select **Save > Dataset**.



Figure 4-29: Active Data Gallery Containing Multiple Stored Datasets



# 5

## **USING VISION64**

This chapter explains basic Vision64 operations and describes the user interface. For full instructions on using Vision64, see its online Help.

**NOTE** – For instructions on Vision64 software features that control the DektakPro profiler, see Chapter 3.

## **OPENING VISION64**

Select **Start**»**Vision64** or double-click the Vision64 application button on the desktop or task bar. The Vision64 Welcome screen appears, followed by the Vision64 Instrument tab, which includes the DektakPro Live Video Display.

Vision64 requires a software key to run (see Figure 5-1). If the key is not installed in a USB port, an error message appears. If this occurs, install the key and restart Vision64.



Figure 5-1: Software Key in a USB Port

## **CLOSING VISION64**

Click the **Exit** button in the upper right-hand corner. When you are prompted to confirm that you want to exit the program, click **Yes**.

Alternatively, you can close Vision64 by clicking the Vision64 application button on the taskbar followed by **Close Window**.

## **IMPORTANT VISION64 DIRECTORIES**

The Vision64 application directory, C:\Program Files\Bruker\Vision64, holds the Vision64 executable code. The directory C:\ProgramData\Bruker\Vision64 holds data and configuration information for the Vision64 application.

## **USING THE VISION64 ONLINE HELP**

**IMPORTANT!** Online assistance in using Vision64 is immediately available through the Vision **Help** menu. This extensive Help system should always be your main source of information about using the Vision64.

## Finding a Help Topic

To display Help in the Vision64 software, select **Help** > **Help Contents** (see Figure 5-2) or press the F1 key to open the Help Tab.



Figure 5-2: Help Button on the Vision64 Ribbon Tab

You can click into another Display Tab to change the contents of the Main Display Area and then return to the same Help topic by re-selecting the Help Tab.

The Help opens to a Table of Contents (on the left) and an introduction to Vision64. Help topics can be selected by clicking one of the following buttons in the left panel of the Help Tab:

- **Contents** lets you browse the Table of Contents. Double-click on a "book" (major heading) to view its "pages" (individual topics). Double-click on a page to view the topic.
- **Index** lets you view search terms that can help you locate topics. Type in the first few letters of the word or phrase that you are looking for. The scrolling list displays that portion of the alphabetical display. Double-click on a topic in the list to display it.
- **Search** lets you search for any word in the Help system. Type the word you want to find in the field provided. Then double-click on a found topic to view its information.
- Favorites displays the topics that you have previously added to a list.

At the top of the Help Tab, **Print**, **Back**, **Forward**, **Home**, **Refresh**, **Stop**, and **Add to Favorites** buttons allow you to navigate the system.

## SELECTING WINDOWS FOR DISPLAY

Click the Windows button on the toolbar. From the list, select the windows that you want to display (see Figure 5-3).

Current View  Measurement Setup  Automation Editor  Live Video	Measurement Auton Setup Se	nation Data tup Acquisition	Data Analysis	Windows	<b>V</b> Reset	
□ Instrument Control □ Database □ Data Acquisition □ Data Analysis □ Data Analysis □ Data Analyzer □ Analysis Toolbox	Cu	rrent View		Measu Auton Live V Instrue Datab Data A V Data A V Active Data A Analys	urement Setup nation Editor ideo ment Control ase Acquisition Analysis Gallery Analyzer sis Toolbox	*

Figure 5-3: Vision64 Window Selection Buttons and Menu

## **WORKING WITH VISION VIEWS**

The Vision64 workspace can simultaneously display one or more of the following Vision View windows, which appear in Figure 5-3 through Figure 5-7:

- Measurement Setup
- Automation Setup
- Data Acquisition
- Data Analysis (which includes the Data Analyzer and Analysis Toolbox if Raw Data is selected)

You can change the size and layout of each Vision View by clicking and dragging with the mouse. You can save each configuration by clicking Save > Vision Views. If you save your preferred set of Vision Views as the startup, it will appear each time that you start Vision64.

Click the **Reset** button to return to the factory-set configuration of the currently displayed Vision View. Click **Reset All** to return to all of the factory-set configurations of all four of the Vision



Measurement S	etup			_×
Measurement Op	ptions			۲
Trace				
Scan Type:	Standard Scan 🔹	Length:	2000	μm Ҟ
Range: (	6.5 μm 🔻	Duration:	10.0	sec
Brofile		Resolution:	0.667	μm/pt
Frome.		Sample:	3000	pts
Stylus Type: (	Radius: 12.5 μm 🔹	] Speed:	200	μm/s
Stylus Force:	3 mg			
Additional Para	ameters			
	📝 Tower Up After Scan 🗌	Use Soft Touch	ndown	
Advanced Option	ns			
Data Stitching				۲
3D Map				۲

Figure 5-4: Measurement Setup Vision View



Figure 5-5: Automation Setup Vision View







Figure 5-7: Data Analysis Vision View



Figure 5-8: Data Analyzer



Figure 5-9: Analysis Toolbox

## **DISPLAYING OTHER VISION64 WINDOWS**

In addition to the four Vision Views, you can display the following items:

- The Live Video Display that gives you a live view of your sample and the stylus (see Figure 5-10).
- The Instrument Control Panel that allows you to control the DektakPro profiler (see Figure 5-11).
- The Active Gallery Display that simultaneously displays thumbnail views of all active datasets. It appears below the Data Analysis Vision View (see Figure 5-12).
- The Database Display that shows statistical analysis results in a comma-separated variable file (see Figure 5-13).
**NOTE** – To use the Analysis toolbox: Click an icon to immediately apply it to the active dataset. Right-click an icon to open an analysis setup dialog box. The Analysis Toolbox is available only when Raw Data is selected in the Data Analyzer.



Figure 5-10: Live Video Display



Figure 5-11: Instrument Control Panel for the X-Y Stage



Figure 5-12: Active Gallery with Multiple Datasets

	Total_Pa	Total_Pt	
	μm	μm	Prot
Measurement Number	R: 0 mm	R: 0 mm	PIO
	M: 49.9833 µm	M: 49.9833 µm	
	Always	Always	
1	0.02852	0.6589	
2	0.02737	0.5220	
3	0.02843	0.6687	
4	0.02453	0.6149	
Avg:	0.02721	0.6161	
Avg: Std:	0.02721 0.00161	0.6161 0.0580	
Avg: Std: Skewness:	0.02721 0.00161 -0.90764	0.6161 0.0580 -0.7822	
Avg: Std: Skewness: Max:	0.02721 0.00161 -0.90764 0.02852	0.6161 0.0580 -0.7822 0.6687	
Avg: Std: Skewness: Max: Min:	0.02721 0.00161 -0.90764 0.02852 0.02453	0.6161 0.0580 -0.7822 0.6687 0.5220	
Avg: Std: Skewness: Max: Min: Range:	0.02721 0.00161 -0.90764 0.02852 0.02453 0.00399	0.6161 0.0580 -0.7822 0.6687 0.5220 0.1467	
Avg: Std: Skewness: Max: Min: Range: Pass:	0.02721 0.00161 -0.90764 0.02852 0.02453 0.00399 4	0.6161 0.0580 -0.7822 0.6687 0.5220 0.1467 4	

Figure 5-13: A DektakPro Database

## **MORE FEATURES OF THE INTERFACE**

**Application Menu Button** Use this button to open the Application Menu, from which you can access the most common Vision64 application functions (see Figure 5-14).



Figure 5-14: Application Menu

**Ribbon** This taskbar (see Figure 5-15) provides access to all of the functions available in Vision64. Note that the most commonly used buttons are permanently displayed to the left and right of each tab on the Ribbon.

**Ribbon Tabs** Click these tabs to make the Ribbon display the **Analyze** Tab (see Figure 5-15), the **Instrument** Tab, or the **Preferences** Tab. You can perform the functions on these tabs by clicking a button or by using keyboard shortcuts. Some tabs include split-buttons that provide multiple related commands.

Instrument	Analyze	Preferences	;											
Measurement Pause C	ancel (	Spen Save	Set Current As	Copy To	Print	() Help	Bruker.con	Create / Edit Database	Measurement	Automation	Data	Data	Windows	<b>O</b> Reset
•			Default	Clipboard •					Setup	Setup	Acquisition	Analysis	•	
Measurement		Files	Data Analyzer			Mi	scellaneous			Current \	/iew		Current W	/indows
1 · · · ·								V .						

Figure 5-15: Ribbon with the Analyze Ribbon Tab Selected

# CHANGING THE UNITS AND OTHER USER PREFERENCES

You can specify different units before or after a scan measurement. After you have done this, the data plot, scan parameters, measurement parameters, ranges, and analytical function calculations all appear in the new units that you have specified.

To change units before or after a scan measurement:

- 1 On the **Preferences** tab of the Ribbon, click the **Units and Numbers** button 🥢.
- 2 Make your settings in the **Units** dialog box (see Figure 3-15), and then click **OK**.

Units			×
Lateral (X,Y)	)	Height (Z) –	
• Metric	C English	Metric	C English
Unit	-	Unit	-
Decimal	•	Decimal	-
Area		Volume	
• Metric	C English	Metric	C English
Unit	<b>_</b>	Unit	<b>_</b>
Decimal	•	Decimal	•
Angular —		Slope	
• Metric	C English	Metric	C English
Unit	<b>_</b>	Unit	<b>_</b>
Decimal	•	Decimal	•
Pressure		Other Units	
• Metric	O English	Decimal	-
Unit	<b>_</b>		
Decimal	<b>_</b>		
Set A	I Units in Metric Set All Unit	ts in English	OK Cancel

Figure 5-16: Units Dialog Box

## **APPLYING FILTERS**

To apply a filter to the active dataset, click **Profile Filter** in the Data Analyzer (see Figure 5-8) or Analysis Toolbox (see Figure 5-9). Then click **Edit Settings** (in the Data Analyzer) or **Edit Default Settings** (in the Analysis Toolbox). The following dialog box appears.

🔷 Surface Profile	e Filter Settings
Filter Type:	Gaussian Regression 👻
Short Cutoff (A	Gaussian 2RC Spline Gaussian Regression Second Order Gaussian Regression Robust Gaussian Regression Second Order Robust Gaussian Regression
Total Profi	le
O Primary Pr	rofile
Roughnes	s Profile
Waviness	Profile
	OK Cancel

#### Figure 5-17: Surface Profile Filter Settings Dialog Box

Select the filter that you want to apply. If this is a Gaussian filter, select **Apply Short Cutoff** or **Apply Long Cutoff** to determine the frequency cutoff wavelength. In the **Output** section, select the type of profile in which you want to view the output. Click **OK**. The system applies the selected filter to the active dataset.

To apply a Terms Removal (F-Operator) or Micro Form filter, click it in the Analysis Toolbox (seeFigure 5-9). To change the settings, right-click it prior to its application.

## **PERFORMING ANALYSES**

To perform an analysis on the active dataset, click the analysis (for example, **Bearing Ratio**) that you want to apply in the Analysis Toolbox (see Figure 5-9). To change the analysis settings, right-click the analysis and select **Edit Default Settings** prior to performing it. Make your selections and click **OK**. The dialog box for the Bearing Ratio analysis appears in Figure 5-18.

Bearing Ratio Analysis	×
Number of Bins: 1000 Bearing Ratio Offsets Peak Offset: 0% - Valley Offset: 0% -	OK Cancel
Bearing Ratio Heights Upper (tp1): 0% Lower (tp2): 100%	

Figure 5-18: Bearing Ratio Analysis Dialog Box

## **3D MAPPING Option**

If your Vision64 software includes the 3D Mapping Option, the user interface and workflow operate somewhat differently than described in this chapter. For example, the Data Visualization Taskbar allows you to quickly change the displayed plot while the Combo Plot drop-down list lets you select combination plots for display (see Figure 5-19). For more information about the 3D Mapping Option, see your Vision64 online Help.



Figure 5-19: Data Visualization Taskbar and Combo Plot Drop-down List



6

## Wafer Warpage Measurement

## Principle

Wafer Warpage Map allows user to measure shape of wafer or any round substrate up to respectively 200mm for Dektak-Pro. It consists of measuring multiples profiles from one edge to the opposite edge of wafer/substrate passing through its center, at incremental theta angles. All single profilers are then bundled together with same common height value of zero at center prior interpolation. Result shows resulting topography with average plane removed.



On left, principle for Wafer Warpage Map. On right, resulting topography with high points in red and low points in blue.

## Getting started with Wafer Warpage Map

Since Wafer Warpage Map consists of measuring over long scan range with aim to accurately assess shape and form, large stylus such as 12.5µm is recommended. It will help to filter out details while ensuring no impact from stylus to the sample even at highest load.

On Measurement Tab, go to Measurement section, select "Radial Map" then populate then the measurement settings for each radial profile in the same section:

#### 1. Measurement length:

90% of total diameter is usually safe value since some wafers have flat reducing diameter for certain profiles. It also ensures best description of overall bow/shape while avoiding edge effects. The latter is critical in case Wafer Warpage Map will be further used for Film Stress calculation.

If the scan length exceeds 55mm, Vision64 software automatically enables Stitching option which allows seamless synchronization of Y motorized axis and stylus scanner to assembled multiple scans via common overlap regions. The total measurement length can reach up to 200mm without any user input.

#### 2. Scan time:

Default time automatically chosen by Vision64 software ensures proper balance between accuracy of shape measurement and total measurement time. Typical scan time for 100mm length is 60 seconds. If user chooses a too aggressive scan time, e.g. too fast scanning, Vision64 automatically discards the value flagging it in red for safe operation. In such case, increase scan time until parameter window remains white.

#### 3. Force

Best practice is to combine large stylus like 12.5µm with maximum force of 15mg. It ensures best repeatable and reproducible conditions for fast profile measurement leading to higher throughput for full radial map. Dektak through its unique in-built head allows safe and quick exchange of stylus allow multiple users to select most suitable stylus for each of their respective applications.

It is not recommended to use stylus below 2µm radius in wafer warpage map measurement. Whenever application requires high lateral, both force and scan speed must be lowered. Enable low force option using force below 1mg and dramatically reduce scan speed to allow stylus to track fine topography details.

## Start Wafer Warpage Map

One measurement setting is defined for scanning profile, place wafer or round sample on chuck. It is important to properly center the sample on chuck to benefit for best performances. For regular wafer sizes (2" till 8", 25mm till 200mm diameters), use the set of stop screws on chuck and place sample against them. For notch type of wafer, use 2 screws while for flat, prefer using 3 screws. For all other sample, approximately center it on the chuck.

#### 1. Set Wafer Warpage Map settings

Once sample is centered on chuck, click on Radial Map button to determine

- Theta Extend: 360° covers the full shape while 180°, 90° respectively cover half and quarter of sample
- Theta Resolution: angular distance between each profile across the center of sample.
   Synchronized with Number of Diameter Lines. Minimum: 1°
- Number of Diameter Lines: number of profiles across the center of sample. Synchronized with Theta Resolution. Maximum: 180
- Re-Null Tower: define if at start of each profile, stylus head re-centers and reset height to zero

Following parameters provides efficient radial map results:

- Theta Extend: 360°
- Theta Resolution: 18°
- Number of Diameter Lines: 10
- Scan Offset: 0µm
- Re-Null Tower: No

#### 2. Define center of sample

For accurate topography, center of sample must be precisely known. Every time that sample size changes and/or stop screw are not in use, user must re-define the center of sample to avoid artifacts and inconsistent results.

For sample center, click on button is to launch Part Center Location. Follow instructions from this window using XY stage to move and center red fiducial at sample border. While there is inherent freedom to choose location versus what software requests, it is critical to sustain precise positioning over sample edge every time.



When all locations are done, click on Finish. Vision64 automatically drives stage such as stylus is located at defined center of sample. All the radial map measurement must start from this position. To recover

this important position, conveniently click on button 📟 "

#### "Move to Center"

#### 3. Launch Measurement

To initiate the radial map, click on top ribbon "Measurement" Measurement.

*Warning:* Pay attention that clicking Single Measurement button only triggers acquisition for single profile starting from center position. Immediately Cancel the measurement to avoid stylus scanning all the way out from sample.



Vision64 initiates the first line profile moving from sample center to the front edge, then performing acquisition of full profiler that includes some iterations in case of stitching. Once first scan is completed, stylus returns to wafer center to re-do the full profiler measurement after theta rotation corresponding to exact Theta Resolution. Prior scan, Vision64 slightly corrects XY starting position to ensure second profile indeed intersects the sample center again. Once all profiles are recorded, system finishes by two extra profiles to automatically compensate tip/tilt of wafer chuck and to optimize topography accuracy.



## Analyze topography

Right after completion of acquisition, system conveniently works out topography and calls the Wafer Bow Analysis. Topography is rendered with colors: red for high and blue for low datapoints. Analysis also works out height difference between highest and lowest datapoint through Pt value. Such output is also known as PV or Flatness.



Since it is a real topography map, user can bring cursors to different locations as well as select radial section through right click on topography image. Each section can also show several useful parameters by showing the Watch List where local slope or radius of curvature between R and M cursors can be live worked out.





## Analyze stress

By measuring full wafer topography before and after thin film deposition, it is possible to measure residual stress in the deposited film through change of local curvatures. Stress calculation process is straightforward. Open radial map from wafer after film deposition then add Stress Analysis. Right-Click on Stress to Edit Setting. In Stress Parameter window, select substrate and film composition through Editor button then indicate thickness for substrate and film in micron units. Finally select the radial map from wafer before deposition and click OK to launch stress calculation.



## Troubleshooting

#### 1. Strong edge effects

This phenomenon appears when scan profile reaches out wafer edges causing spurious distortion during topography map building. Two main factors are possibly involved and even combined:

- a) Too long scanning length
- b) Stylus starting position is not at wafer center
- c) Wafer has flat that lowers the actual diameter of wafer at certain theta position(s)

Apply following steps to clear the issue:

- 1. In scan settings, use the wizard to define the start and end of scan no less than 5mm away from wafer edge. Adjust this 5mm limit with respect to expected diameter at flat position
- 2. In Radial Map settings, click on Move to Center. Visually confirm that stylus indeed seems at center of wafer
- 3. In case of doubt, re-run the Part Center Location

#### 2. Shape distortion

This phenomenon appears whenever stylus is way off from wafer center or center of rotation is now well calibrated. It is critical that while rotation occurs, system can back-calculate exact new XY position to be at wafer edge and scan to go through wafer center.



Same sample without proper centering (Left) and with proper calibration (Right) of wafer center as well as center of theta rotation

Apply following steps to clear the issue:

- 1. Re-Run Theta Center of Rotation with step height standard or any sample with clearly identified feature on it
- 2. Place back sample for radial map and re-run Part Center location
- 3. Re-run measurement

## **Automatic Step Measurement**

A step height transition between cursor positions on a Dektak trace measurement defines the height which could be a material step height, a etch depth, material deposit or even a film thickness. A new Analyzer was implemented called Auto Step Correction to easily and automatically calculate a step height transition and width of a step if present based on the automatic positioning of cursors with respect to a step edge along with automatic setting of the cursor widths. This step along with multiple steps in one trace measurement can be calculated and logged into a database. In addition to the new auto step method. As with any analyser the user has the freedom to tailor more advanced analysis by setting up preprocessing of the data with multiple analyses via the analysis tree.

#### **SOAP Key:**

The Auto Step Correction is currently under SOAP key control called "Advanced ASH (Auto Step Height)" and needs to be enabled for use.

DXT 3D Stress DXT N-Lite Radial Mapping Advanced ASH

#### **SETUP:**

The Auto Step GUI interface is designed for simple setup as seen in here. NOTE: It is good measurement practice to perform necessary filtering before the Auto Step analysis.

21	D Analysis		
	Auto Step	Correction	
AutoStepCorrectionUI			×
<ul> <li>Level the profile using the</li> </ul>	e reference	line	
Results           Image: Show results for nega           Image: Show Individual value           Image: Show Average value	ative steps a: es	s negative values	
Horizontal descrimination	2.5	% of Length	
Vertical descrimination	25	% of Height	
	ОК	Cancel	Advanced

#### • Horizontal discrimination

- This parameter is a percentage of the total scan length used for cursor placement for step measurement and leveling of scan cursor placement.
- The cursor placements are offset from the first step transitions with this horizontal lateral percentage.
  - EXAMPLE: If a scan length is 2mm with a 2.5% horizontal setting
    - 2000um \* 0.025 = 50um

 $\circ$   $\;$  The measurement cursor will be placed 50um in from and 50um behind the first step transition.

 When entering ADVANCED a visual representation of this can be seen and modified by adjusting the cursor placement and size and then enabling USE ADVANCED PARAMETERS.



 Default settings are generally good unless ASH cursors aren't shown.

#### • Vertical discrimination

- This parameter is a percentage of the total vertical step height detected which is used for edge detection (same as Pt).
  - EXAMPLE: from the above graph: If a step height is 10000A with a 25% vertical setting
    - 1000um \* 0.25 = 250um
  - This mean detection will have ±250um from mean line on the spline fit data.



- With large step(s) the default 25% is typically good
- For varying heights or very small steps this value may need to be lowered for steps to be detected.

#### • Level the profile using the reference line

- By default, this should be checked and used to level the profile for accurate step measurement but may not be needed if pre-leveling is sufficient.
- Advanced setup of leveling is in the ADVANCED>DATA LEVELING SETTINGS using the typical default level setting parameters.

Leveling Type None Two Point Linear Fit Linear & Curvature Removal Type Linear v Circle Removal Data Region for Leveling Calculations Use full data set Use full data set Use data between R and M Cursor Exclude data between R and M Cursor Cursor Positioning Label Position (mm) Width (mm) R 0.0000 0.0000 M 0.0999 0.0000		Leveling Settings	
None         Two Point Linear Fit         Linear & Curvature Removal         Type       Linear         O Circle Removal         Data Region for Leveling Calculations         Use full data set         Use data between R and M Cursor         Exclude data between R and M Cursor         Cursor Positioning         Label       Position (mm)         Width (mm)         R       0.0000         M       0.0999         0.0000       0.0000	Leveling	Туре	
Two Point Linear Fit <ul> <li>Linear &amp; Curvature Removal</li> <li>Type</li> <li>Linear</li> <li>Circle Removal</li> </ul> Data Region for Leveling Calculations <ul></ul>	O None	•	
<ul> <li>Linear &amp; Curvature Removal Type Linear          <ul> <li>Circle Removal</li> </ul> </li> <li>Data Region for Leveling Calculations         <ul> <li>Use full data set</li> <li>Use data between R and M Cursor</li> <li>Exclude data between R and M Cursor</li> </ul> </li> <li>Cursor Positioning         <ul> <li>Label Position (mm) Width (mm) R 0.0000 0.0000 <u>0.0999 0.0000</u> </li> </ul> </li> </ul>		Point Linear Fit	
Type     Linear       Circle Removal       Data Region for Leveling Calculations          ● Use full data set        Use data between R and M Cursor       Exclude data between R and M Cursor       Cursor Positioning       Label     Position (mm)       R     0.0000       M     0.0999       0.0000     0.0000	Linea	r & Curvature Remo	val
Circle Removal         Data Region for Leveling Calculations <ul> <li>Use full data set</li> <li>Use data between R and M Cursor</li> <li>Exclude data between R and M Cursor</li> </ul> Cursor Positioning         Label       Position (mm)       Width (mm)         R       0.0000       0.0000         M       0.0999       0.0000	Тур	Linear	~
Data Region for Leveling Calculations  Use full data set Use data between R and M Cursor Exclude data between R and M Cursor Cursor Positioning Label Position (mm) Width (mm) R 0.0000 0.0000 0.0000 Δ 0.0999 0.0000 0.000 0.	O Circle	Removal	
<ul> <li>O Use full data set</li> <li>O Use data between R and M Cursor</li> <li>Exclude data between R and M Cursor</li> <li>Cursor Positioning</li> <li>Label Position (mm) Width (mm)</li> <li>R 0.0000 0.0000</li> <li>M 0.0999 0.0000</li> <li>Δ 0.0999</li> </ul>	Data Reg	ion for Leveling Calo	ulations
Use data between R and M Cursor         Exclude data between R and M Cursor         Cursor Positioning         Label       Position (mm)         Width (mm)         R       0.0000         M       0.0999         Δ       0.0999	Use f	ull data set	
Exclude data between R and M Cursor           Cursor Positioning           Label         Position (mm)         Width (mm)           R         0.0000         0.0000           M         0.0999         0.0000           Δ         0.0999         0.0000	O Use o	lata between R and	M Cursor
Cursor Positioning           Label         Position (mm)         Width (mm)           R         0.0000         0.0000           M         0.0999         0.0000           Δ         0.0999         0.0000	0		
Label         Position (mm)         Width (mm)           R         0.0000         0.0000           M         0.0999         0.0000           Δ         0.0999         0.0000	O Exclu	de data between R a	and M Cursor
Label         Position (mm)         Width (mm)           R         0.0000         0.0000           M         0.0999         0.0000           Δ         0.0999         0.0000	() Exclu	de data between R a	and M Cursor
R         0.0000         0.0000           M         0.0999         0.0000           Δ         0.0999         0.0000	Cursor	de data between R a Positioning	and M Cursor
M 0.0999 0.0000 Δ 0.0999	Cursor	de data between R a Positioning Position (mm)	Width (mm)
Δ 0.0999	Cursor Label	de data between R a Positioning Position (mm) 0.0000	Width (mm)
	Cursor Label R M	de data between R a Positioning Position (mm) 0.0000 0.0999	Width (mm) 0.0000 0.0000
	Cursor	de data between R a Positioning Position (mm) 0.0000 0.0999 0.0999	Width (mm) 0.0000 0.0000
Masking	Cursor Label R M A	de data between R a Positioning Position (mm) 0.0000 0.0999 0.0999	Width (mm) 0.0000 0.0000
Use Terms Mask	Cursor Label R M Δ	de data between R a Positioning Position (mm) 0.0000 0.0999 0.0999	Width (mm) 0.0000 0.0000
Edit Mask	Cursor Label R M Δ Use Edit M.	de data between R a Positioning Position (mm) 0.0000 0.0999 0.0999 Terms Mask ask	Width (mm) 0.0000 0.0000
Masking Use Terms Mask Edit Mask	Cursor Label R M Δ Masking Use Edit M	de data between R a Positioning 0.0000 0.0999 0.0999 Terms Mask ask	Width (mm) 0.0000 0.0000
Calculate Close	Cursor Label R M Δ Masking Use Edit M	de data between R a Positioning Position (mm) 0.0000 0.0999 0.0999 Terms Mask ask Calculate	M Cursor Width (mm) 0.0000 0.0000

Results

#### • Show results of negative steps as negative values

- Negative step values can be outputted as positive if checked.
- Show Individual value
  - Reports all cursor value positions with measurement results if checked.
- Show Average values
  - Report the average value of measurements on multiple steps traces if checked.

#### ANALYSIS:

Results of a 1um step with defaults setting



#### **DATABASE:**

With a trace loaded and the analysis working properly, the database can now be setup. Depending on the step and the number of them will determine the options within the database.

#### **Numerics**

3D Mapping Option 2-9

#### Α

Analysis Toolbox 4-21, 5-6 Analytical functions, appending 4-13 Analyzer recipes 4-20 Application Menu button 5-9 Auto Stages 2-3 Automated measurements 4-10 Automation Editor 4-10 Automation recipes 4-10

#### В

Base feet 2-5 Bridge 2-3

## С

Calibrating the system 3-17 Camera 2-3 Chucks for 3D mapping and automation 2-3 Computer 2-6, 2-7 Configuring the system 3-17 Cursor locations and bandwidths, setting 4-14

## D

Data Analyzer 4-20, 5-6 Database Creating 4-18 Example 5-9 Data-stitching software 2-9 DektakPro Stylus Profiler Components described 2-3 Configuring and calibrating 3-17 Electronics 2-4 Environmental enclosure 2-6, 4-4 Illustrated 2-2 DektakPro Stylus Profiler - cont. Options and accessories 2-8 Principle of operation 2-2 Scanning operation 4-8

#### Ε

Electrical task classification 1-5 Electronics 2-4 Emergency Off button 1-1 EMO box 2-6, 3-2 Environmental enclosure 2-6, 4-4

## Н

Hazards Mechanical 1-4 Pressure 1-4 Help, using Vision64 5-2

## L

Illumination, adjusting 3-5 Installation of the system, safety issues 1-4 Intensity bar 3-5

## L

Leveling the stage 3-6 Linear Variable Differential Transformer 2-2 Loading and unloading sample 3-4 Lockout procedures 1-5

#### Μ

Maintenance of the system 1-4, 3-17 Manually leveling the stage 3-6 Measurement, sequence of events 4-7 Measurement head, described 2-3 Measurement Options, setting 4-2 Measurements, scan Automated 4-10 Manual 4-4 Mechanical hazards 1-4 Meta data, selecting and viewing 4-22 Monitor 2-7, 2-8

#### 0

Online help 5-2 Optics, adjusting illumination 3-5

#### Ρ

Power On and Off switches 1-2 Power supply adapter 2-4, 2-5 Powering down 3-3 Powering up 3-1 Pressure hazards 1-4

#### R

Ribbon in Vision64 5-10 Ribbon tabs 5-10

#### S

Safety features Emergency Off button 1-1 Power On and Off switches 1-2 Safety precautions 1-2 Sample fixtures for stages 2-3 Scanning process 4-8 Signal processor 2-5 Software key 3-1 Software leveling 4-16 Stage Configurations 2-2 Controlling the X-Y auto 2-3 Controlling the theta auto 3-9 Manually leveling 3-6 Sample fixtures (chucks) 2-3 Using the manual positioning controls 3-6 Step height standard 2-9 Stored data, viewing and analyzing 4-23 Stylus Cleaning the tip 3-16 Removing 3-13 Installing a new 3-10

#### Т

Theta stage control 3-9 Tower assembly 2-3 Towering up and down 3-5 Turning on the system 3-1

#### U

Units, changing 5-10 User preferences, changing 5-10

#### V

Vision recipes 4-22 Vision Views 5-3 Vision64 Closing 5-1 Described 2-2, 2-7 Directories 5-2 Elements of the workspace 5-3 Interface explained 5-1 Online help 5-2 Opening 5-1 Selecting windows for display 5-3 Starting 3-2 Vision Views 5-3

#### W

Wafer vacuum sample fixture 2-3

#### Х

X-Y auto stage, manually leveling 3-6